Distributed by: M.A. Selmon Company, Inc 4 Oxford Rd. Milford, CT 06460 203-377-3525

# V200-18-E3XB Snap-in I/O Module

The V200-18-E3XB plugs directly into the back of compatible Unitronics OPLCs, creating a self-contained PLC unit with a local I/O configuration.

#### **Features**

- 18 isolated digital inputs, includes 2 H.S.C inputs, type pnp/npn (source/sink)
- 15 isolated relay outputs
- 2 isolated pnp/npn (source/sink) transistor outputs, includes 2 H.S. outputs
- 4 isolated analog/PT100/TC inputs
- 4 isolated analog outputs
- Before using this product, it is the responsibility of the user to read and understand this document and any accompanying documentation.
- All examples and diagrams shown herein are intended to aid understanding, and do not guarantee
  operation. Unitronics accepts no responsibility for actual use of this product based on these
  examples.
- Please dispose of this product in accordance with local and national standards and regulations.
- Only qualified service personnel should open this device or carry out repairs.

#### User safety and equipment protection guidelines

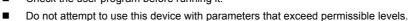
This document is intended to aid trained and competent personnel in the installation of this equipment as defined by the European directives for machinery, low voltage, and EMC. Only a technician or engineer trained in the local and national electrical standards should perform tasks associated with the device's electrical wiring.

Symbols are used to highlight information relating to the user's personal safety and equipment protection throughout this document. When these symbols appear, the associated information must be read carefully and understood fully.

Symbol	Meaning	Description		
1	Danger	The identified danger causes physical and property damage.		
<u>^</u> !\	Warning	The identified danger can cause physical and property damage.		
Caution	Caution	Use caution.		



- Failure to comply with appropriate safety guidelines can result in severe personal injury or property damage. Always exercise proper caution when working with electrical equipment.
- Check the user program before running it.





- Install an external circuit breaker and take appropriate safety measures against shortcircuiting in external wiring.
- To avoid damaging the system, do not connect / disconnect the device when the power is on

Caution

Ascertain that terminal blocks are properly secured in place.

#### **Environmental Considerations**



 Do not install in areas with: excessive or conductive dust, corrosive or flammable gas, moisture or rain, excessive heat, regular impact shocks or excessive vibration.



- Provide proper ventilation by leaving at least 10mm of space between the top and bottom edges of the device and the enclosure walls.
- Do not place in water or let water leak onto the unit.
- Do not allow debris to fall inside the unit during installation.

# Wiring



- Do not touch live wires.
- <u>^</u>!\
- Unused pins should not be connected. Ignoring this directive may damage the device.
- Do not connect the 'Neutral' or 'Line' signal of the 110/220VAC to the device's 0V pin.
- Double-check all wiring before turning on the power supply.

# **Wiring Procedures**

Use crimp terminals for wiring; use 26-12 AWG wire (0.13 mm  $^2$ -3.31 mm $^2$ ) for all wiring purposes.

- 1. Strip the wire to a length of 7±0.5mm (0.250–0.300 inches).
- 2. Unscrew the terminal to its widest position before inserting a wire.
- 3. Insert the wire completely into the terminal to ensure that a proper connection can be made.
- 4. Tighten enough to keep the wire from pulling free.
- To avoid damaging the wire, do not exceed a maximum torque of 0.5 N·m (5 kgf·cm).
- Do not use tin, solder, or any other substance on stripped wire that might cause the wire strand to break
- Install at maximum distance from high-voltage cables and power equipment.

#### I/O Wiring—General

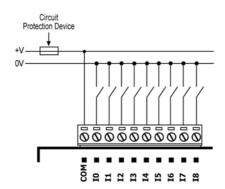
- Input or output cables should not be run through the same multi-core cable or share the same
- Allow for voltage drop and noise interference with input lines used over an extended distance.
   Use wire that is properly sized for the load.

# **Digital Inputs**

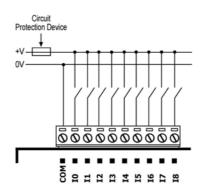
Each group of 9 inputs has a common signal. Each group can be used as either pnp (source) or npn (sink), when appropriately wired as shown in the following figures.

Inputs I0 and I2 can be used as normal digital inputs, as high-speed counters, or as part of a shaft encoder. Inputs I1 and I3 can be used as normal digital inputs, as high-speed counter resets, or as part of a shaft encoder.

# npn (sink) digital input wiring

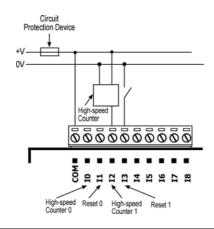


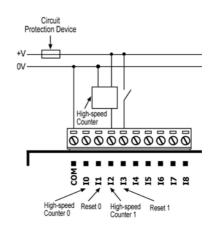
pnp (source) digital input wiring



npn (sink) high-speed counter

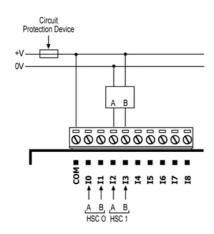
pnp (source) high-speed counter



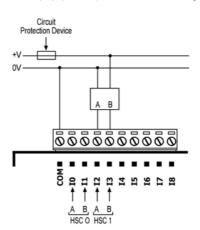


Inputs I0, I1, and I2, I3 can be used as shaft encoders as shown below.

npn (sink) shaft encoder wiring



pnp (source) shaft encoder wiring

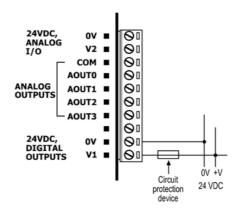


# **Digital Outputs**

# **Wiring Power Supplies**

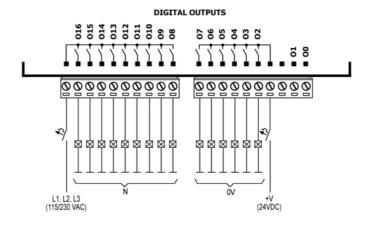
Use a 24VDC power supply for both relay and transistor outputs.

- Connect the "positive" lead to the "V1" terminal, and the "negative" lead to the "0V" terminal.
- In the event of voltage fluctuations or nonconformity to voltage power supply specifications, connect the device to a regulated power supply



# **Relay Outputs**

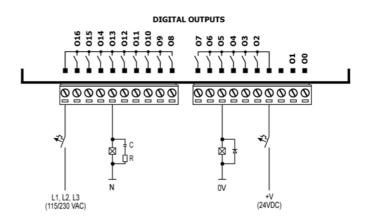
- Each output can be wired separately to either AC or DC as show below.
- The 0V signal of the relay outputs is isolated from the controller's 0V signal.



# **Increasing Contact Life Span**

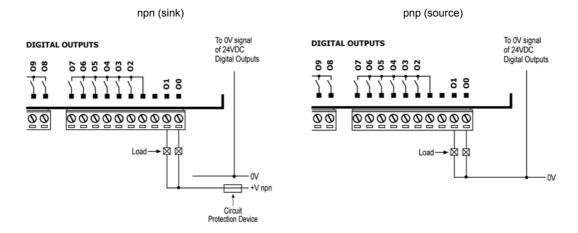
To increase the life span of the relay output contacts and protect the device from potential damage by reverse EMF, connect:

- a clamping diode in parallel with each inductive DC load,
- an RC snubber circuit in parallel with each inductive AC load.



#### **Transistor Outputs**

- Each output can function as either npn or pnp, in accordance with jumper settings and wiring. Open the device and set the jumpers according to the instructions beginning on page 8.
- The 0V signal of the transistor outputs is isolated from the controller's 0V signal.



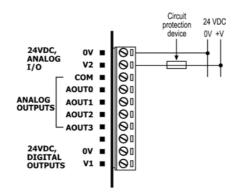
# **Analog I/O Power Supplies**

Use a 24VDC power supply for all analog input and output modes.

- 1. Connect the "positive" cable to the "V2" terminal, and the "negative" to the "0V" terminal.
- In the event of voltage fluctuations or non-conformity to voltage power supply specifications, connect the device to a regulated power supply.
- Since the analog I/O power supply is isolated, the controller's 24VDC power supply may also be used to power the analog I/Os.



The 24VDC power supply must be turned on and off simultaneously with the controller's power supply.

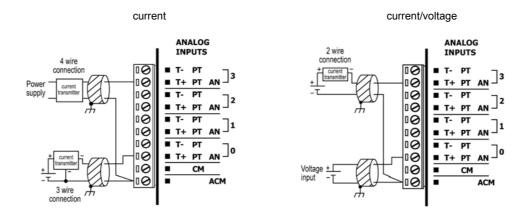


# Analog / PT100 / TC Inputs

- Each input may be set as either analog, RTD, or thermocouple. To set an input:
  - Use the appropriate wiring as shown below.
  - Open the device and set the jumpers according to the instructions beginning on page 8.
- Shields should be connected at the signal source.
- In order to function correctly, the analog power supplies must be wired as shown on page 5.
- To ensure proper performance, a warm-up period of a half an hour is recommended.

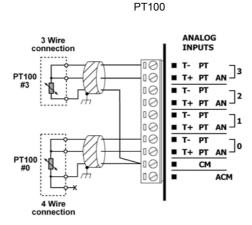
#### **Analog Inputs**

- Inputs may be wired to work with either current or voltage.
- When set to current/voltage, all inputs share a common ACM signal.



#### **RTD Inputs**

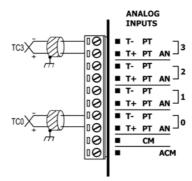
- 1. Wire one lead of each RTD input to the common signal (CM) as shown below.
- 4 wire PT100 can be used by leaving one of the sensor leads unconnected.



# **Thermocouple Inputs**

- Supported thermocouple types include B, E, J, K, N, R, S, and T, in accordance with software and jumper settings. See table Thermocouple Input Ranges, on page 15.
- Inputs may be set to mV by software settings (Hardware Configuration); note that in order to set mV inputs, thermocouple jumper settings are used.

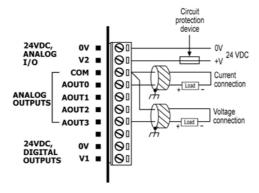
# Thermocouple



# **Analog Outputs**

- Shields should be earthed, connected to the earth of the cabinet.
- An output can be wired to either current or voltage.
  - Use the appropriate wiring as shown below.
  - Open the device and set the jumpers according to the instructions beginning on page 8.
- To ensure proper performance, a warm-up period of a half an hour is recommended.

# current/voltage



# **Changing Jumper Settings**

To access the jumpers, you must remove the snap-in I/O module from the controller, and then remove the module's PCB board. Before you begin, turn off the power supply, disconnect and dismount the controller.

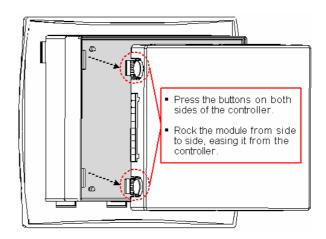


- Before performing these actions, touch a grounded object to discharge any electrostatic charge.
- Avoid touching the PCB board directly by holding the PCB board by its connectors.

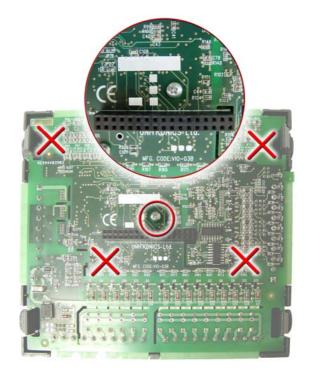
#### **Accessing the Jumpers**

First, remove the snap-in module.

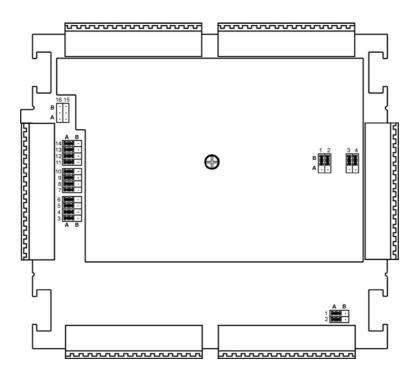
- Locate the 4 buttons on the sides of the module, two on either side. Press the 2 buttons on either side of the module as shown, and hold them down to open the locking mechanism.
- Gently rock the module from side to side, easing the module from the controller.



- Using a Philips screwdriver, remove the center screw, shown in the figure below, from the module's upper PCB board. Do not remove any other screws.
- Holding the PCB board by its edges, gently lift it out of the module.



Select the desired function by changing the jumper settings according to the figure and tables shown below.



**Analog Input Jumpers** 

Analog Input Jumpers							
		Jumper #	Voltage*	Current	T/C or mV	PT100	
	Analog input 3	14	Α	В	В	Α	
		13	Α	В	В	Α	
		12	Α	Α	В	В	
	Analog input 2	11	Α	В	В	Α	
		10	Α	В	В	Α	
		9	Α	Α	В	В	
<b>Bottom PCB board</b>	Analog input 1	8	Α	В	В	Α	
		7	Α	В	В	Α	
		6	Α	Α	В	В	
	Analog input 0	5	Α	В	В	Α	
		4	Α	В	В	Α	
		3	Α	Α	В	В	
	Digital Output Jumpers						
Note that Jumpers #15 & 16 are not used		Jumper #	PNP*	NPN			
	Digital Output 0	1	Α	В			
	Digital Output 1	2	Α	В	_		

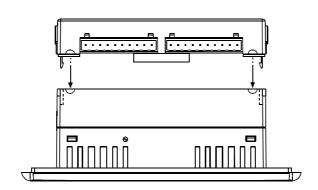
Δna	nol	Oi	itnut	.lun	npers

	7 that by Catput Campore			
		Jumper #	Current	Voltage*
Tan BOD has and	Analog Output 0	1	Α	В
Top PCB board	Analog Output 1	2	Α	В
	Analog Output 2	3	Α	В
	Analog Output 3	4	Α	В

<sup>\*</sup> Default factory setting

# Reassembling the controller

- 1. Return the PCB board to the module and secure the center screw.
- 2. Next, reinstall the module. Line the circular guidelines on the controller up with the guidelines on the Snap-in I/O Module as shown below.
- Apply even pressure on all 4 corners until you hear a distinct 'click'. The module is now installed. Check that all sides and corners are correctly aligned.



# V200-18-E3XB Technical Specifications

**Digital Inputs** 

Number of inputs 18 (in two groups) Input type pnp (source) or npn (sink)

Galvanic isolation

Digital inputs to bus Yes Digital inputs to digital inputs No

in same group

Group to group, digital inputs Yes Nominal input voltage 24VDC

Input voltage

npn (sink)

0-5VDC for Logic '0' pnp (source)

17-28.8VDC for Logic '1' 17-28.8VDC for Logic '0' 0-5VDC for Logic '1'

Input current 6mA@24VDC for inputs #4 to #17

8.8mA@24VDC for inputs #0 to #3

Response time 10mSec typical

High speed inputs Specifications below apply when these inputs are wired for use as a high-

speed counter input/shaft encoder. See Notes 1 and 2.

Resolution 32-bit

Frequency 10kHz maximum

Minimum pulse width 40µs

#### Notes:

- Inputs #0 and #2 can each function as either high-speed counter or as part of a shaft encoder. In each case, high-speed input specifications apply. When used as a normal digital input, normal input specifications apply.
- Inputs #1 and #3 can each function as either counter reset, or as a normal digital input; in either case, its specifications are those of a normal digital input. These inputs may also be used as part of a shaft encoder. In this case, high-speed input specifications apply.

# **Digital Outputs**

#### **Digital Output's Power Supply**

Nominal operating voltage 24VDC

20.4 to 28.8VDC Operating voltage 20mA@24VDC. Quiescent current

85mA@24VDC. See Note 3. Max. current consumption

Galvanic isolation

Digital power supply to Yes

Digital power supply to

relay outputs

Yes

Digital power supply to No

transistor outputs

# Notes:

Maximum current consumption does not provide for PNP output requirements. The additional current requirement of PNP outputs must be added.

**Relay Outputs** 

Number of outputs 15 relays (in two groups). See Note 4.

Output type SPST-NO (Form A)

Isolation By relay

Tyco PCN-124D3MHZ or compatible Type of relay Outputs' power supply See Digital Output's Power Supply above

Galvanic isolation

Yes Relay outputs to bus Group to group, relay Yes

outputs

Relay to transistor outputs Yes

Output current 3A maximum per output (resistive load)

8A maximum total for common (resistive load)

Rate voltage 250VAC / 30VDC Minimun load 1mA@5VDC

Life expectancy 100k operations at maximum load

Response time 10mS (typical)

Contact protection External precautions required (see Increasing Contact Life Span, p.4)

Notes:

Outputs #2,3,4,5,6 and 7 share a common signal. Outputs #8,9,10,11,12,13,14,15 and 16 share a common signal

**Transistor Outputs** 

Number of outputs 2, high-speed. Each can be individually set as pnp (source) or npn (sink) via

wiring and jumper settings. See Note 5.

pnp: P-MOSFET (open drain) Output type

npn: N-MOSFET (open drain)

Galvanic isolation

Transistor outputs to bus Yes Transistor outputs to No

transistor outputs

Transistor outputs to relay

outputs

Output current pnp: 0.5A maximum per output

Yes

npn: 50mA maximum per output

Maximum frequency Resistive load

pnp: 2kHz npn: 50kHz Inductive load 0.5Hz

pnp: 0.5VDC maximum ON voltage drop

npn: 0.4VDC maximum

Short circuit protection Yes (pnp only)

pnp (source) power supply See Digital Output's Power Supply above

npn (sink) power supply

operating voltage 3.5V to 28.8VDC.

unrelated to the voltage of either the I/O module or the controller

Notes:

Both transistor outputs may be used as high-speed outputs.

Analog I/O's Power Supply

Nominal operating voltage 24VDC

Operating voltage 20.4 to 28.8VDC
Quiescent current 70mA@24VDC
Max. current consumption 130mA@24VDC

Galvanic isolation

Analog power supply to bus Yes
Analog power supply to Yes
analog inputs

Analog power supply to Yes analog outputs

Analog/ PT100/ TC Inputs

Number of inputs 4

Type of input Set via appropriate wiring and jumper settings.

**Analog Inputs Power Supply** 

Galvanic isolation

Analog/PT/TC inputs to bus Yes
Analog/PT/TC inputs to Yes
analog outputs

Analog /PT/TC inputs to Analog /PT/TC inputs

**Analog inputs** 

Input range 0-10V, 0-20mA, 4-20mA

Power supply See Analog I/O's Power Supply above

No

Conversion method Succesive approximation
Resolution at 0-10V, 14-bit (16384 units). See Note 6.
0-20mA

Resolution at 4-20mA 3277 to 16384 (13107 units). See Note 6.

Conversion time Synchronized to cycle time Input impedance >1M $\Omega$ —voltage

±40mA—current

Full-scale error  $\pm 0.4\%$ Linearity error  $\pm 0.04\%$ 

Status indication Yes. See Note 7.

# Notes:

6. 12 or 14-bit resolution may be selected via software.

7. The analog value can indicate faults as shown below:

ValuePossible Cause16384Input value deviates slightly above the input range32767-Input value deviates greatly above or below the input range

-Power supply disconnected

PT100 inputs

Input range -200 to  $600^{\circ}$ C/-328 to  $1100^{\circ}$ F. 1 to  $320\Omega$ . See Note 8.

Conversion method Voltage to frequency

Resolution 0.1°C/0.1°F

Conversion time 200mS minimum per channel, depending on software filter type

 $\begin{array}{lll} \text{Input impedance} & > 10 \text{M}\Omega \\ \text{Auxillary current for PT100} & 150 \mu \text{A typical} \\ \text{Full-scale error} & \pm 0.4 \% \\ \text{Linearity error} & \pm 0.04 \% \end{array}$ 

Status indication Yes. See Note 9.

#### Notes:

8. The device can also measure resistance with the range of 1-320  $\Omega$  at a resolution of 0.1  $\Omega$ .

9. The analog value can indicate faults as shown below:

Value Possible Cause

32767 - Sensor is not connected to input
- Value exceeds permissible range
- Power supply disconnected

-32767 Sensor is short-circuited

Thermocouple inputs

Input range As shown in the table on page 15. See Note 10.

Conversion method Voltage to frequency
Resolution 0.1°C/0.1°F maximum

Conversion time 100mS minimum per channel, depending on software filter type

Input impedance  $>10M\Omega$ 

Cold junction compensation Local, automatic

Cold junction compensation  $\pm 1.5^{\circ}\text{C}$  /  $\pm 2.7^{\circ}\text{F}$  maximum

error

Absolute maximum rating ±0.6VDC Full-scale error ±0.4% Linearity error ±0.04%

Warm-up time ½ hour typically, ±1°C/±1.8°F repeatability

Status indication Yes. See Note 11.

#### Notes:

The device can also measure voltage within the range of -5 to 56mV, at a resolution of 0.01mV.
 The device can also measure raw value frequency at a resolution of 14-bits(16384)

11. The analog value can indicate faults as shown below:

Value Possible Cause

32767 - Sensor is not connected to input

- Sensor value exceeds the maximum value

- Power supply disconnected

-32767 Sensor value is under the minimum value

Table 1: Thermocouple input ranges

Туре	Temperature range	Wire Color		
	•	ANSI (USA)	BS 1843 (UK)	
mV	-5 to 56mV	-	-	
В	200 to 1820°C	+Grey	+None	
	(300 to 3276°F)	-Red	-Blue	
Е	-200 to 750°C	+Violet	+Brown	
	(-328 to 1382°F)	-Red	-Blue	
J	-200 to 760°C	+White	+Yellow	
	(-328 to 1400°F)	-Red	-Blue	
K	-200 to 1250°C	+Yellow	+Brown	
	(-328 to 2282°F)	-Red	-Blue	
N	-200 to 1300°C	+Orange	+Orange	
	(-328 to 2372°F)	-Red	-Blue	
R	0 to 1768°C	+Black	+White	
	(32 to 3214°F)	-Red	-Blue	
S	0 to 1768°C	+Black	+White	
	(32 to 3214°F)	-Red	-Blue	
Т	-200 to 400°C	+Blue	+White	
	(-328 to 752°F)	-Red	-Blue	

#### **Analog Outputs**

Number of outputs 4 (single-ended)

Output range 0-10V, 4-20mA. See Note 12.

Resolution 12-bit (4096 units)

 $\begin{array}{lll} \text{Conversion time} & & \text{Synchronized to scan time.} \\ \text{Load impedance} & & 1 k \Omega \text{ minimum-voltage} \\ & & 500\Omega \text{ maximum-current} \end{array}$ 

Galvanic isolation

Analog outputs to bus Yes
Analog outputs to Yes
Analog/PT/TC inputs

Analog outputs to analog No outputs

Linearity error  $\pm 0.1\%$ Operational error limits  $\pm 0.2\%$ 

# Notes:

12. Note that the range of each I/O is defined by wiring, jumper settings, and within the controller's software.

Environmental IP20 / NEMA1

Operating temperature 0° to 45°C (32° to 113°F)
Storage temperature -20° to 60° C (-4° to 140°F)
Relative Humidity (RH) 5% to 90% (non-condensing)
Dimensions (WxHxD) 138x23x123mm (5.43x0.9x4.84")

Weight 279g (9.87 oz)

#### **About Unitronics**

Unitronics has been producing PLCs, automation software and accessory devices since 1989.

Unitronics' OPLC controllers combine full-function PLCs and HMI operating panels into single, compact units. These HMI + PLC devices are programmed in a single, user-friendly environment. Our clients save I/O points, wiring, space, and programming time; elements that translate directly into cost-efficiency.

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For more information regarding Unitronics products, contact your distributor or Unitronics headquarters via email:  $\underbrace{\mathsf{export} @\mathsf{unitronics}.\mathsf{com}}_{}.$ 



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